

Solving Models with Heterogeneous Agents - KS algorithm

Wouter J. Den Haan
London School of Economics

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Individual agent

- Subject to employment shocks ($e_{i,t} \in \{0,1\}$)
- Incomplete markets
 - only way to save is through holding capital
 - borrowing constraint $k_{i,t+1} \geq 0$

Laws of motion

- z_t can take on two values
- e_t can take on two values
- probability of being (un)employed depends on z_t
- transition probabilities are such that unemployment rate only depends on current z_t . Thus:
 - $u_t = u^b$ if $z_t = z^b$
 - $u_t = u^g$ if $z_t = z^g$
 - with $u^b > u^g$.

Individual agent

$$\max_{\{c_{i,t}, k_{i,t+1}\}_{t=0}^{\infty}} E \sum_{t=0}^{\infty} \beta^t \ln(c_{i,t})$$

s.t.

$$\begin{aligned} c_{i,t} + k_{i,t+1} &= r_t k_{i,t} + (1 - \tau_t) w_t \bar{l} e_{i,t} + \mu w_t (1 - e_{i,t}) + (1 - \delta) k_{i,t} \\ k_{i,t+1} &\geq 0 \end{aligned}$$

for **given** processes of r_t and w_t , this is a relatively simple problem

Firm problem

$$r_t = a_t \alpha \left(\frac{K_t}{\bar{l}(1 - u(a_t))} \right)^{\alpha-1}$$
$$w_t = a_t (1 - \alpha) \left(\frac{K_t}{\bar{l}(1 - u(a_t))} \right)^\alpha$$

Government

$$\tau_t w_t \bar{l}(1 - u(a_t)) = \mu w_t u(a_t)$$

$$\tau_t = \frac{\mu u(a_t)}{\bar{l}(1 - u(a_t))}$$

What aggregate variables do agents care about?

- r_t and w_t
- They only depend on aggregate capital stock and z_t
- !!! This is not true in general for equilibrium prices
- Agents are interested in all information that forecasts K_t
- In principle that is the complete cross-sectional distribution of employment status and capital levels

Equilibrium - first part

- Individual policy functions solving agent's max problem
- A wage and a rental rate given by equations above.

Equilibrium - second part

- A transition law for the cross-sectional distribution of capital, that is consistent with the investment policy function.

$$f_{t+1} = Y(z_{t+1}, z_t, f_t)$$

- f_t = beginning-of-period cross-sectional distribution of capital and the employment status after the employment status has been realized.
- z_{t+1} does not affect the cross-sectional distribution of capital but does affect the joint cross-sectional distribution of capital and employment status

Key approximating step

- ① Approximate cross-sectional distribution with limited set of "characteristics"
 - Proposed in Den Haan (1996), Krusell & Smith (1997,1998), Rios-Rull (1997)
- ② Solve for aggregate policy rule
- ③ Solve individual policy rule for a given aggregate law of motion
- ④ Make the two consistent

Krusell-Smith (1997,1998) algorithm

- Assume the following approximating aggregate law of motion

$$m_{t+1} = \bar{\Gamma}(z_{t+1}, z_t, m_t; \eta_{\bar{\Gamma}}).$$

- Start with an initial guess for its coefficients, $\eta_{\bar{\Gamma}}^0$

Krusell-Smith (1997,1998) algorithm

- Use following iteration until $\eta_{\bar{\Gamma}}^{iter}$ has converged:
 - Given $\eta_{\bar{\Gamma}}^{iter}$ solve for the individual policy rule
 - Given individual policy rule simulate economy and generate a time series for m_t
- Use a regression analysis to update values of η

$$\eta_{\bar{\Gamma}}^{iter+1} = \lambda \hat{\eta}_{\bar{\Gamma}} + (1 - \lambda) \eta_{\bar{\Gamma}}^{iter}, \text{ with } 0 < \lambda \leq 1$$

Solving for individual policy rules

- Given aggregate law of motion \implies you can solve for individual policy rules with your favourite algorithm
- But number of state variables has increased:
 - State variables for agent: $s_{i,t} = \{k_{i,t}, e_{i,t}, a_t\}$
 - with $a_t = \{z_t, m_t\} = \{z_t, K_t, \tilde{m}_t\}$.

Solving for individual policy rules

- a_t must "reveal" K_t
 - $a_t \implies K_t \implies r_t^k$ and r_t^w
- Let $K_{t+1} = \bar{\Gamma}_K(z_{t+1}, z_t, a_t; \eta_{\bar{\Gamma}})$, $\tilde{m}_{t+1} = \bar{\Gamma}_{\tilde{m}}(z_{t+1}, z_t, a_t; \eta_{\bar{\Gamma}})$
- If a_t includes many characteristics of the cross-sectional distribution \implies high dimensional individual policy rule

Individual policy rules & projection methods

First choice to make:

- Which function to approximate?
- Here we approximate $k_i(\cdot)$

$$k_{i,t+1} = P_n(s_{i,t}; \eta_{P_n})$$

- N_η : dimension η_{P_n}

Individual policy rules & projection methods

Next: Design grid

- s_κ the κ^{th} grid point
- $\{s_\kappa\}_{\kappa=1}^\chi$ the set with χ nodes
- $s_\kappa = \{k_\kappa, e_\kappa, a_\kappa\}$, and $a_\kappa = \{z_\kappa, K_\kappa, \tilde{m}_\kappa\}$

Individual policy rules & projection methods

Next: Implement projection idea

- ① Substitute approximation into model equations until you get equations of only
 - ① current-period state variables
 - ② coefficients of approximation, η_{P_n}
- ② Evaluate at χ grid points $\implies \chi$ equations to find η_{P_n}
 - $N_\eta = \chi \implies$ use equation solver
 - $N_\eta > \chi \implies$ use minimization routine

Individual policy rules & projection methods

First-order condition

$$c_t^{-\nu} = E \left[\frac{\beta(r^k(z', K') + (1 - \delta)) \times c_{t+1}^{-\nu}}{} \right]$$

$$(\text{income}_{i,t} - k_{i,t+1})^{-\nu} = E \left[\frac{\beta(r^k(z', K') + (1 - \delta)) \times (\text{income}_{i,t+1} - k_{i,t+2})^{-\nu}}{} \right]$$

Individual policy rules & projection methods

First-order condition

$$\begin{pmatrix} (r^k(z_\kappa, K_\kappa) + 1 - \delta)k_\kappa \\ +(1 - \tau(z_\kappa))r^w(z_\kappa, K_\kappa)\bar{l}e_\kappa + \mu r^w(z_\kappa, K_\kappa)(1 - e_\kappa) \\ -P_n(s_\kappa; \eta_{P_n}) \end{pmatrix}^{-\nu}$$

$$= E \left[\begin{pmatrix} \beta(r^k(z', K') + (1 - \delta)) \times \\ (r^k(z', K') + 1 - \delta)P_n(s_\kappa; \eta_{P_n}) \\ +(1 - \tau(z'))r^w(z', K')\bar{l}e' + \mu r^w(z', K')(1 - e') \\ -P_n(s'; \eta_{P_n}) \end{pmatrix}^{-\nu} \right]$$

Individual policy rules &projection methods

Euler equation errors:

$$u_\kappa = \left(\begin{array}{c} (r^k(z_\kappa, K_\kappa) + 1 - \delta)k_\kappa \\ +(1 - \tau(z_\kappa))r^w(z_\kappa, K_\kappa)\bar{e}_\kappa + \mu r^w(z_\kappa, K_\kappa)(1 - e_\kappa) \\ -P_n(s_\kappa; \eta_{P_n}) \end{array} \right)^{-\nu} -$$

$$\sum_{z' \in \{z^b, z^g\}} \sum_{e' \in \{0, 1\}} \left[\left(\begin{array}{c} \beta(r^k(z', K') + (1 - \delta)) \times \\ (r^k(z', K') + 1 - \delta)P_n(s_\kappa; \eta_{P_n}) \\ +(1 - \tau(z'))r^w(z', K')\bar{e}' \\ +\mu r^w(z', K')(1 - e') \\ -P_n(s'; \eta_{P_n}) \\ \pi(e', z' | z_\kappa, e_\kappa) \end{array} \right)^{-\nu} \times \right]$$

Error depends on known variables and η_{P_n} when using

$$\begin{aligned} r^k(z_\kappa, K_\kappa) &= \alpha z_\kappa (K_\kappa / L(z_\kappa))^{\alpha-1} \\ r^w(z_\kappa, K_\kappa) &= (1 - \alpha) z_\kappa (K_\kappa / L(z_\kappa))^\alpha \end{aligned}$$

$$\begin{aligned} r^k(z', K') &= \alpha z' (K' / L(z'))^{\alpha-1} \\ &= \alpha z' (\bar{\Gamma}_K(z', z_\kappa, a_\kappa; \eta_{\bar{\Gamma}}) / L(z'))^{\alpha-1} \\ r^w(z', K') &= (1 - \alpha) z' (K' / L(z'))^\alpha \\ &= (1 - \alpha) z' (\bar{\Gamma}_K(z', z_\kappa, a_\kappa; \eta_{\bar{\Gamma}}) / L(z'))^\alpha \end{aligned}$$

$$\tau(z) = \mu(1 - L(z)) / \bar{l}L(z)$$

$$s' = \left\{ \begin{array}{c} k', e', z', \\ \bar{\Gamma}_K(z', z_\kappa, a_\kappa; \eta_{\bar{\Gamma}}), \bar{\Gamma}_{\tilde{m}}(z', z_\kappa, a_\kappa; \eta_{\bar{\Gamma}}) \end{array} \right\}$$

Again standard projection problem

- Find η_{P_n} by minimizing $\sum_{\kappa=1}^{\chi} u_{\kappa}^2$

Remaining issues

- ➊ Using just the mean and approximate aggregation
- ➋ Simulation
- ➌ Other models and always ensuring equilibrium

Approximate aggregation

- The mean is often sufficient $\not\Rightarrow$ close to complete markets
- Why does only the mean matter?

Approximate aggregation

- Approximate aggregation \equiv
 - Next period's prices can be described quite well using
 - exogenous driving processes
 - means of current-period distribution
- Approximate aggregation
 - \neq aggregates behave as in RA economy
 - with *same* preferences
 - with any preferences
 - \neq individual consumption behaves as aggregate consumption

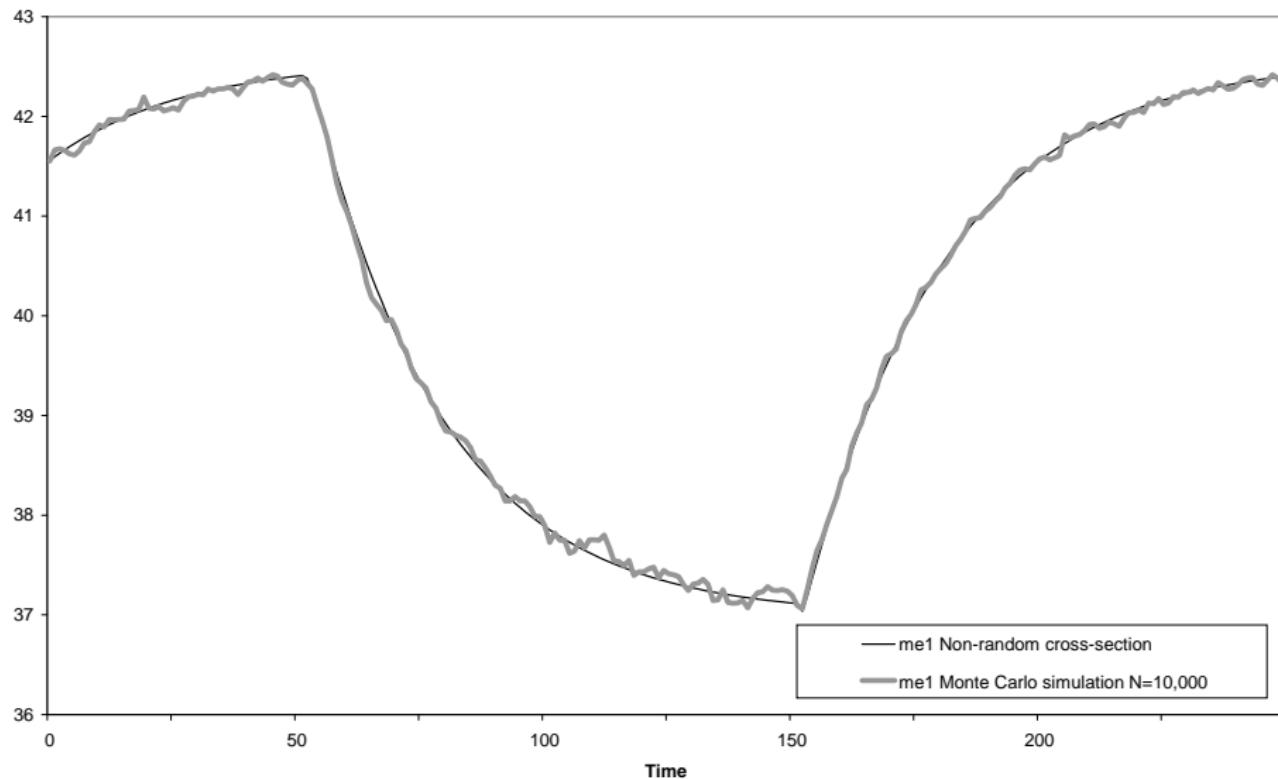
Why approximate aggregation

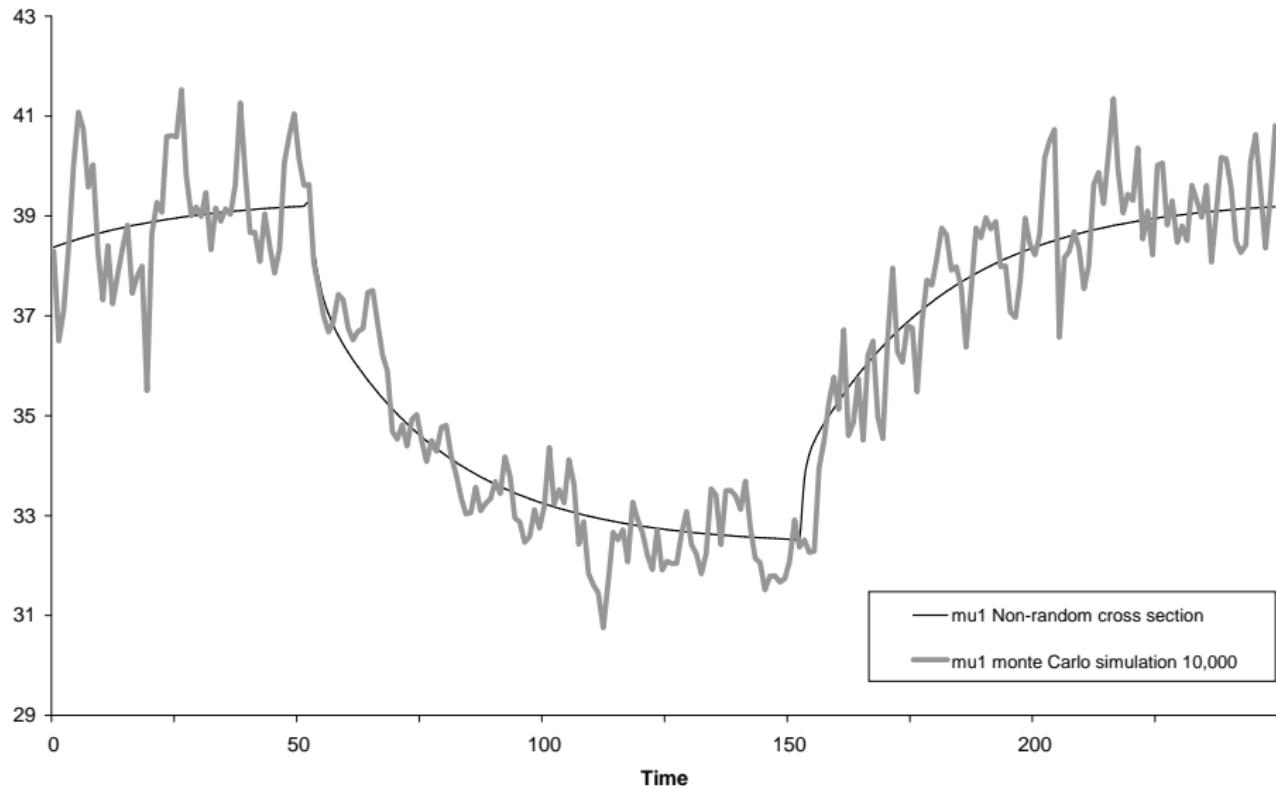
- If policy function *exactly* linear in levels
 - so also not loglinear
- then redistributions of wealth don't matter at all \Rightarrow
Only mean needed for calculating next period's mean
- Approximate aggregation still possible with non-linear policy functions
 - but policy functions must be sufficiently linear where it matters

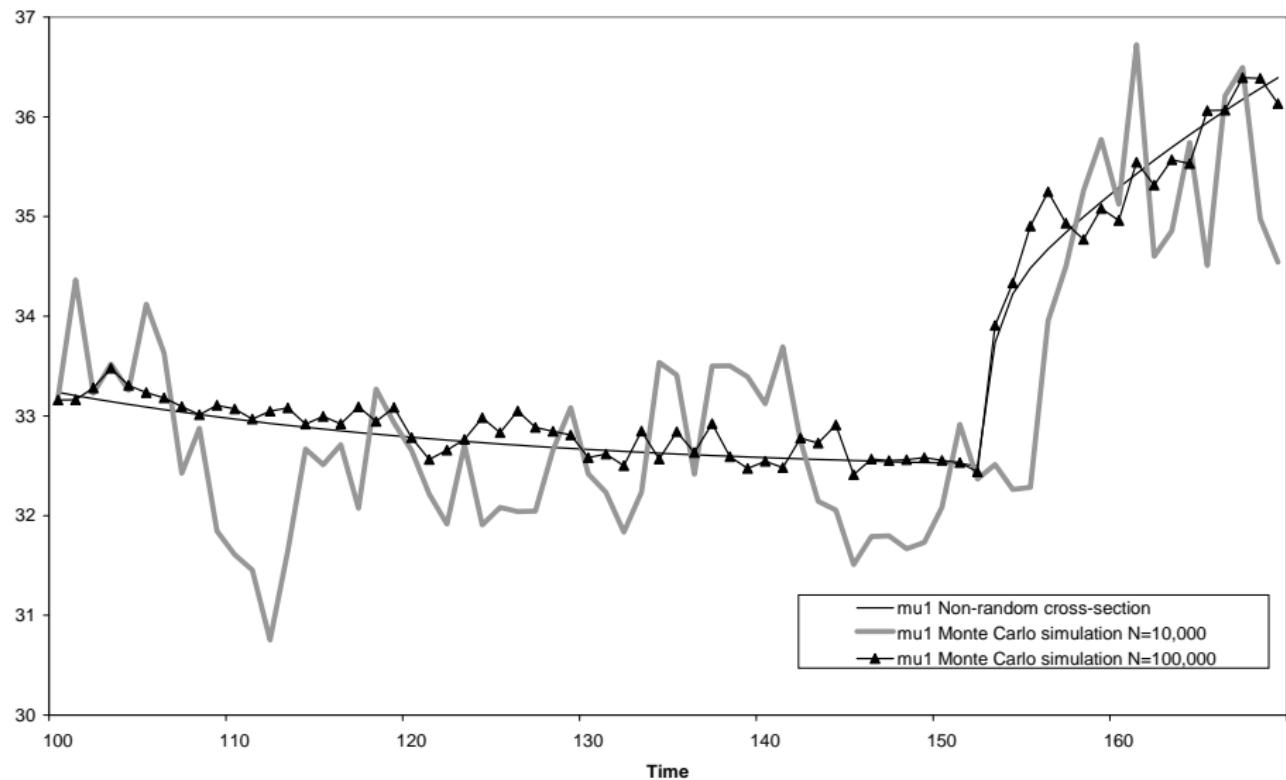
How to simulate?

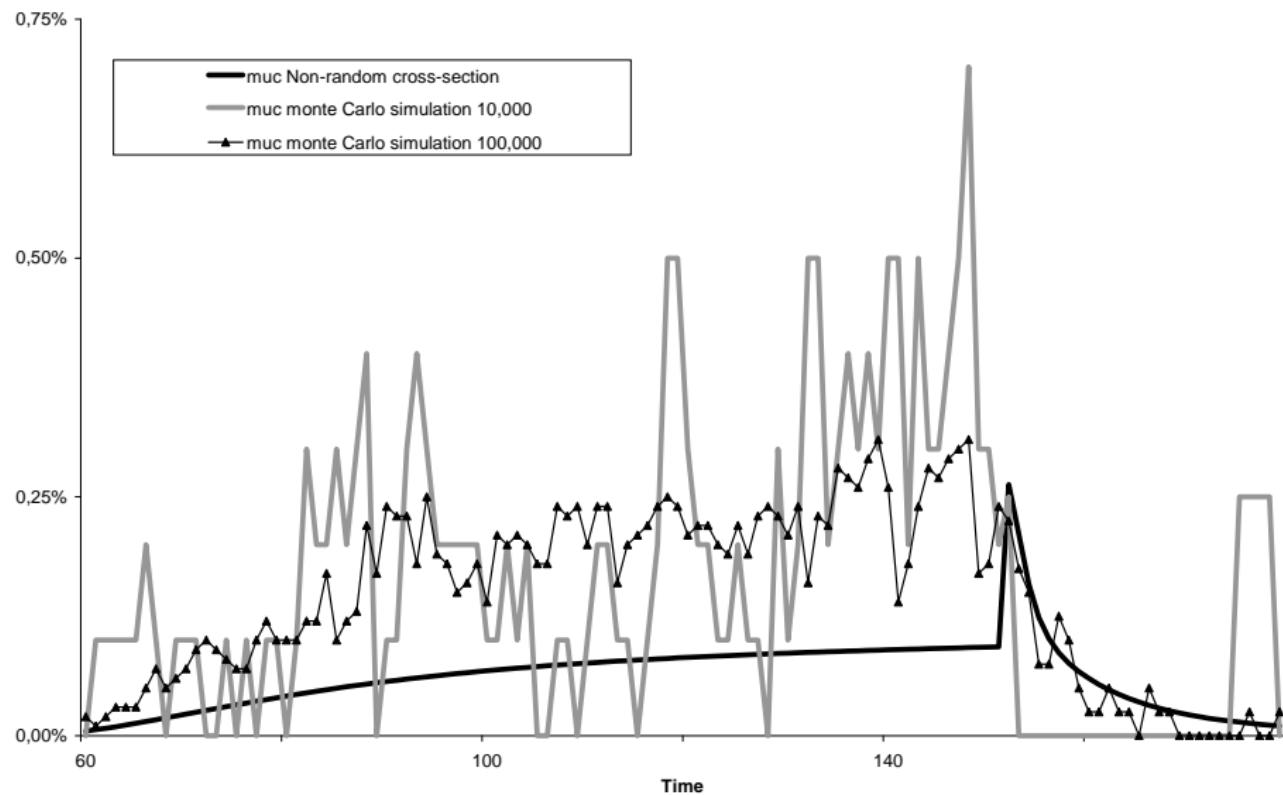
- Numerical procedure with a continuum of agents
- What if you really do like to simulate a panel with a finite number of agents?
 - Impose truth as much as possible: if you have 10,000 agents have exactly 400 (1,000) agents unemployed in a boom (recession)
 - Even then sampling noise is non-trivial

Simulation and sampling noise









Imposing equilibrium

- In model above, equilibrium is automatically imposed in simulation
- Why?

Imposing equilibrium

- What if we add one-period bonds?
 - Also solve for
 - individual demand for bonds, $b(s_{i,t})$
 - bond price, $q(a_t)$
 - Simulated aggregate demand for bonds not necessarily = 0
 - Why is this problematic?

Bonds and ensuring equilibrium I

- Add the bond price as a state variable in individual problem
 - a bit weird (making endogenous variable a state variable)
 - risky in terms of getting convergence

Bonds and ensuring equilibrium II

- Don't solve for

$$b_i(s_{i,t})$$

- but solve for

$$b_i(q_t, s_{i,t})$$

- where dependence on q_t comes from an equation

- Solve q_t from

$$0 = \left(\sum b_i(q_t, s_{i,t}) \right) / I$$

Bonds and ensuring equilibrium II

How to get $b_i(q_t, s_{i,t})$?

① Solve for $d_i(s_{i,t})$ where

$$d(s_{i,t}) = b(s_{i,t}) + q(a_t)$$

- this adds an equation to the model

② Imposing equilibrium gives

$$\begin{aligned} 0 &= \left(\sum b_i(q_t, s_{i,t}) \right) / I \implies \\ q_t &= \left(\sum d_i(s_{i,t}) \right) / I \\ b_{i,t+1} &= d(s_{i,t}) - q(a_t) \end{aligned}$$

Bonds and ensuring equilibrium II

- Does any $b_i(q_t, s_{i,t})$ work?
- For sure it needs to be a demand equation, that is

$$\frac{\partial b_i(q_t, s_{i,t})}{\partial q_t} < 0$$

Bonds and ensuring equilibrium II

Many ways to implement above idea:

- $d(s_{i,t}) = b(s_{i,t}) + q(a_t)$ is ad hoc (no economics)
- Alternative:
 - solve for $c(s_{i,t})$
 - get $b_{i,t}$ from budget constraint which contains q_t
 - You get $b_i(q_t, s_{i,t})$ with

$$\frac{\partial b_i(q_t, s_{i,t})}{\partial q_t} < 0$$

KS algorithm: Advantages & Disadvantages

- simple
- MC integration to calculate cross-sectional means
 - can easily be avoided
- Points used in projection step are clustered around the mean
 - Theory suggests this would be bad (recall that even equidistant nodes does not ensure uniform convergence; Chebyshev nodes do)
 - At least for the model in KS (1998) this is a non-issue; in comparison project the aggregate law of motion for K obtained this way is the most accurate

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